	Diagnosing Nonlinearity and Other Ills 1 1. Introduction
	 The first three topics of the lecture take up the problems of non-normally distributed errors
	non-constant error variance
	nonlinearity.
9. Diagnosing Nonlinearity And Other Ills	 The treatment here stresses simple graphical methods for detecting these problems, along with transformations of the data to correct problems that are detected.
	Subsequent topics describe tests of non-constant error variance and nonlinearity for discrete explanatory variables; and (time permitting) diagnostic methods based upon imbedding the usual linear model in a more general nonlinear model incorporating transformations as parameters.
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Diagnosing Nonlinearity and Other Ills	2 Diagnosing Nonlinearity and Other Ills 3
2 Goals:	3 Example: The SLID Data

2. Goals:

- ► To introduce simple methods for detecting non-normality, non-constant error variance, and nonlinearity.
- ► To show how these problems can often be corrected by transformation and other approaches.
- ► To introduce the method of maximum likelihood, and to demonstrate its application to regression diagnostics.

3. Example: The SLID Data

- To illustrate the methods described in lecture, I will primarily use data from the 1994 wave of Statistics Canada's Survey of Labour and Income Dynamics (SLID).
- ► The SLID data set that I use includes 3997 employed individuals who were between 16 and 65 years of age and who resided in Ontario.
- Regressing the composite hourly wage rate on a dummy variable for sex (code 1 for males), education (in years), and age (also in years) produces the following results:

$$\begin{split} \widehat{\mathsf{W}} \mathsf{ages} &= -8.124 \ + \ 3.474 \times \mathsf{Male} & + \ 0.2613 \times \mathsf{Age} \\ (0.599) & (0.2070) & (0.0087) \\ & + \ 0.9296 \times \mathsf{Education} \\ & (0.0343) \\ \end{split} \\ R^2 &= \ .3074 \end{split}$$

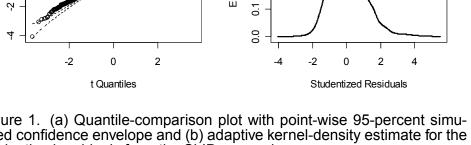
Diagnosing Nonlinearity and Other Ills Diagnosing Nonlinearity and Other Ills Λ A multimodal error distribution suggests the omission of one or more 4. Non-Normally Distributed Errors discrete explanatory variables that divide the data naturally into The assumption of normally distributed errors is almost always arbitrary. groups. but the central-limit theorem assures that inference based on the least-► Quantile-comparison plots are useful for examining the distribution of squares estimator is approximately valid. Why should we be concerned the residuals, which are estimates of the errors. about non-normal errors? • We compare the sample distribution of the studentized residuals, E_{i}^{*} . Although the validity of least-squares estimation is robust the efficiency with the quantiles of the unit-normal distribution, N(0, 1), or with those of least squares is not: The least-squares estimator is maximally of the *t*-distribution for n - k - 2 degrees of freedom. efficient among unbiased estimators when the errors are normal. For heavy-tailed errors, the efficiency of least-squares estimation • Even if the model is correct, the studentized residuals are not an *independent* random sample from t_{n-k-2} . Correlations among the decreases markedly. residuals depend upon the configuration of the X-values, but they are • Highly skewed error distributions, aside from their propensity to generally negligible unless the sample size is small. generate outliers in the direction of the skew, compromise the • At the cost of some computation, it is possible to adjust for the deinterpretation of the least-squares fit as a conditional typical value of pendencies among the residuals in interpreting a quantile-comparison Y. plot. © c Diagnosing Nonlinearity and Other Ills 6 Diagnosing Nonlinearity and Other Ills ► The guantile-comparison plot is effective in displaying the tail behavior of the residuals: Outliers, skewness, heavy tails, or light tails all show up (a) (b) clearly. 0.5 Ordered Studentized Residuals ► Other univariate graphical displays, such as histograms and density 4 0.4 estimates, effectively supplement the quantile-comparison plot. Estimated Density

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- ► Figure 1 shows a t quantile-comparison plot and a density estimate for the studentized residuals from the SLID regression.
 - The distribution of the studentized residuals is positively skewed and there may be more than one mode.
 - The positive skew in the residual distribution can be corrected by transforming the response variable down the ladder of powers, in this case using logs, producing the residual distribution shown in Figure 2.
 - The resulting residual distribution has a slight negative skew, but I preferred the log transformation to the 1/3 power for interpretability.
 - Note that the residual distribution is heavy-tailed and possibly bimodal.



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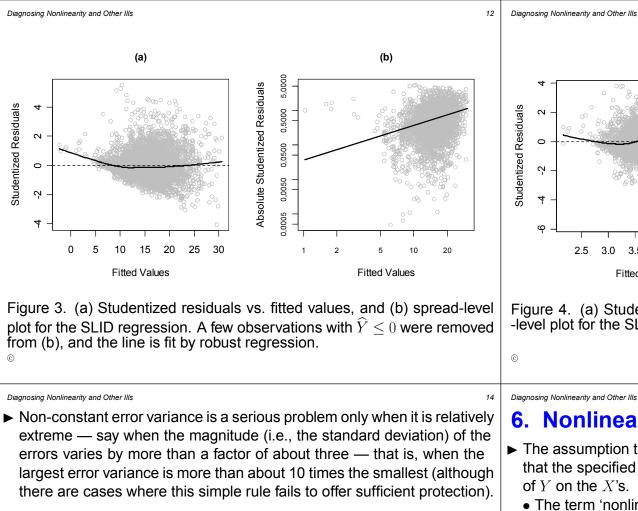
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Figure 1. (a) Quantile-comparison plot with point-wise 95-percent simulated confidence envelope and (b) adaptive kernel-density estimate for the studentized residuals from the SLID regression.

Diagnosing Nonlinearity and Other Ills 8	Diagnosing Nonlinearity and Other IIIs 9
	5. Non-Constant Error Variance
(a) (b) $f_{1} = \frac{1}{2}$ (c) $f_{2} = \frac{1}$	 Although the least-squares estimator is unbiased and consistent even when the error variance is not constant, its efficiency is impaired, and the usual formulas for coefficient standard errors are inaccurate. Non-constant error variance is sometimes termed 'heteroscedasticity.' Because the regression surface is <i>k</i>-dimensional, and imbedded in a space of <i>k</i> + 1 dimensions, it is generally impractical to assess the assumption of constant error variance by direct graphical examination of the data. It is common for error variance to increase as the expectation of <i>Y</i> grows larger, or there may be a systematic relationship between error variance and a particular <i>X</i>. The former situation can often be detected by plotting residuals against fitted values; the latter by plotting residuals against each <i>X</i>.
 Diagnosing Nonlinearity and Other Ills Plotting residuals against Y (as opposed to Ŷ) is generally unsatisfactory, because the plot will be 'tilted' There is a built-in linear correlation between Y and E, since Y = Ŷ + E. The least-squares fit insures that the correlation between Ŷ and E is zero, producing a plot that is much easier to examine for evidence of non-constant spread. Because the <i>residuals</i> have unequal variances even when the variance of the <i>errors</i> is constant, it is preferable to plot studentized residuals against fitted values. It often helps to plot E_i[*] or E_i^{*2} against Ŷ. It is also possible to adapt Tukey's spread-level plot (as long as all of the fitted values are positive), graphing log absolute studentized residuals against log fitted values. 	 Diagnosing Nonlinearity and Other Ills Figure 3 shows a plot of studentized residuals against fitted values and a spread-level plot for the SLID regression. The increasing spread with increasing Ŷ suggests moving Y down the ladder of powers to stabilize the variance. The slope of the line in the spread-level plot is b = 0.9994, suggesting the transformation p = 1 - 0.9994 = 0.0006 ≈ 0 (i.e., the log transformation). After log-transforming Y, the diagnostic plots look much better (Figure 4). There are alternatives to transformation for dealing with non-constant error variance. Weighted-least-squares (WLS) regression, for example, can be used, down-weighting observations that have high variance. It is also possible to correct the estimated standard errors of the ordinary least squares (OLS) estimates for non-constant spread.

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(a) (b) 5.0000 Absolute Studentized Residuals 0.5000 0.0500 0.0050 0.0005 2.5 3.0 3.5 5.0 4.0 4.5 2.5 Fitted Values Fitted Values

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Figure 4. (a) Studentized residuals versus fitted values, and (b) spread--level plot for the SLID regression after log-transforming wages.

- 6. Nonlinearity
- \blacktriangleright The assumption that the average error, $E(\varepsilon)$, is everywhere zero implies that the specified regression surface accurately reflects the dependency of Y on the X's.
 - The term 'nonlinearity' is therefore not used in the narrow sense here, although it includes the possibility that a partial relationship assumed to be linear is in fact nonlinear.
 - If, for example, two explanatory variables specified to have additive effects instead interact, then the average error is not zero for all combinations of X-values.
 - If nonlinearity, in the broad sense, is slight, then the fitted model can be a useful approximation even though the regression surface $E(Y|X_1,...X_k)$ is not captured precisely.
 - In other instances, however, the model can be seriously misleading.

 Diagnosing Nonlinearity and Other Ills The regression surface is generally high dimensional, even after accounting for regressors (such as dummy variables, interactions, and polynomial terms) that are functions of a smaller number of fundamental explanatory variables. As in the case of non-constant error variance, it is necessary to focus on particular patterns of departure from linearity. The graphical diagnostics discussed in this section are two-dimensional projections of the (k + 1)-dimensional point-cloud of observations {Y_i, X_{i1},, X_{ik}}. 	 Diagnosing Nonlinearity and Other Ills 6.1 Component+Residual Plots Although it is useful in multiple regression to plot Y against each X, these plots can be misleading, because our interest centers on the <i>partial</i> relationship between Y and each X, controlling for the other X's, not on the <i>marginal</i> relationship between Y and an individual X, ignoring the other X's. Plotting residuals or studentized residuals against each X is frequently helpful for detecting departures from linearity. As Figure 5 illustrates, however, residual plots cannot distinguish between monotone and non-monotone nonlinearity. The distinction is important because monotone nonlinearity frequently can be 'corrected' by simple transformations.
	- Case (a) might be modeled by $Y = \alpha + \beta \sqrt{X} + \varepsilon$.
Diagnosing Nonlinearity and Other IIIs (a) (b) (b) (c) (c) (c) (c) (c) (c) (c) (c	 Diagnosing Nonlinearity and Other Ills - Case (b) cannot be linearized by a power transformation of <i>X</i>, and might instead be dealt with by the quadratic regression, <i>Y</i> = α + β₁<i>X</i> + β₂<i>X</i>² + ε. ► Added-variable plots, introduced previously for detecting influential data, can reveal nonlinearity and suggest whether a relationship is monotone. These plots are not always useful for locating a transformation, however: The added-variable plot adjusts <i>X_j</i> for the other <i>X</i>'s, but it is the unadjusted <i>X_j</i> that is transformed in respecifying the model.
	 Component+residual plots, also called partial-residual plots (as opposed to partial-regression = added-variable plots) are often an effective alternative. Component+residual plots are not as suitable as added-variable plots for revealing leverage and influence.
Figure 5. The residual plots of E versus X (bottom) are identical, even though the regression of Y on X in (a) is monotone while that in (b) is non-monotone.	• The partial residual for the <i>j</i> th explanatory variable is $E_i^{(j)} = E_i + B_j X_{ij}$

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- In words, add back the linear component of the partial relationship between *Y* and *X_j* to the least-squares residuals, which may include an unmodeled nonlinear component.
- Then plot $E^{(j)}$ versus X_j .
- By construction, the multiple-regression coefficient B_j is the slope of the simple linear regression of $E^{(j)}$ on X_j , but nonlinearity may be apparent in the plot as well.
- The component+residual plots in Figure 6 are for age and education in the SLID regression, using log-wages as the response.
 - Both plots look nonlinear:
 - It is not entirely clear whether the partial relationship of log wages to age is monotone, simply tending to level off at the higher ages, or whether it is non-monotone, turning back down at the far right.

(a) (b) 2 Component + Residual Component + Residual 0 5 Ņ Ņ က္ 20 30 50 60 C 15 20 Education (years) Age (years)

Figure 6. Component-plus-residual plots for age and education in the SLID regression of log wages on these variables and sex. A lowess smooth (span = 0.4) and least-squares line is shown on each graph.

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- The partial relationship of log wages to education is clearly monotone, and the departure from linearity is not great—except at the lowest levels of education, where data are sparse; we should be able to linearize this partial relationship by moving education up the ladder of powers, because the bulge points to the right.
- Trial and error experimentation suggests that the quadratic specification for age works better, producing the following fit to the data:

$$\begin{split} \widehat{\log_2 \text{Wages}} &= 0.5725 + 0.3195 \times \text{Male} + 0.1198 \times \text{Age} \\ (0.0834) & (0.0180) & (0.0046) \\ & - 0.001230 \times \text{Age}^2 + 0.002605 \times \text{Education}^2 \\ (0.000059) & (0.000113) \end{split}$$

Diagnosing Nonlinearity and Other Ills

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22

Diagnosing Nonlinearity and Other Ills

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- We can take two approaches to constructing component+residual plots for this respecified model:
- 1. We can plot partial residuals for each of age and education against the corresponding explanatory variable. In the case of age, the partial residuals are computed as

$$E_i^{(Age)} = 0.1198 \times Age_i - 0.001230 \times Age_i^2 + E_i$$

and for education,

$$E_i^{(\mathsf{Education})} = 0.002605 \times \mathsf{Education}_i^2 + E_i$$

See the upper panels of Figure 7; the solid lines are the *partial fits* (i.e., the components) for the two explanatory variables,

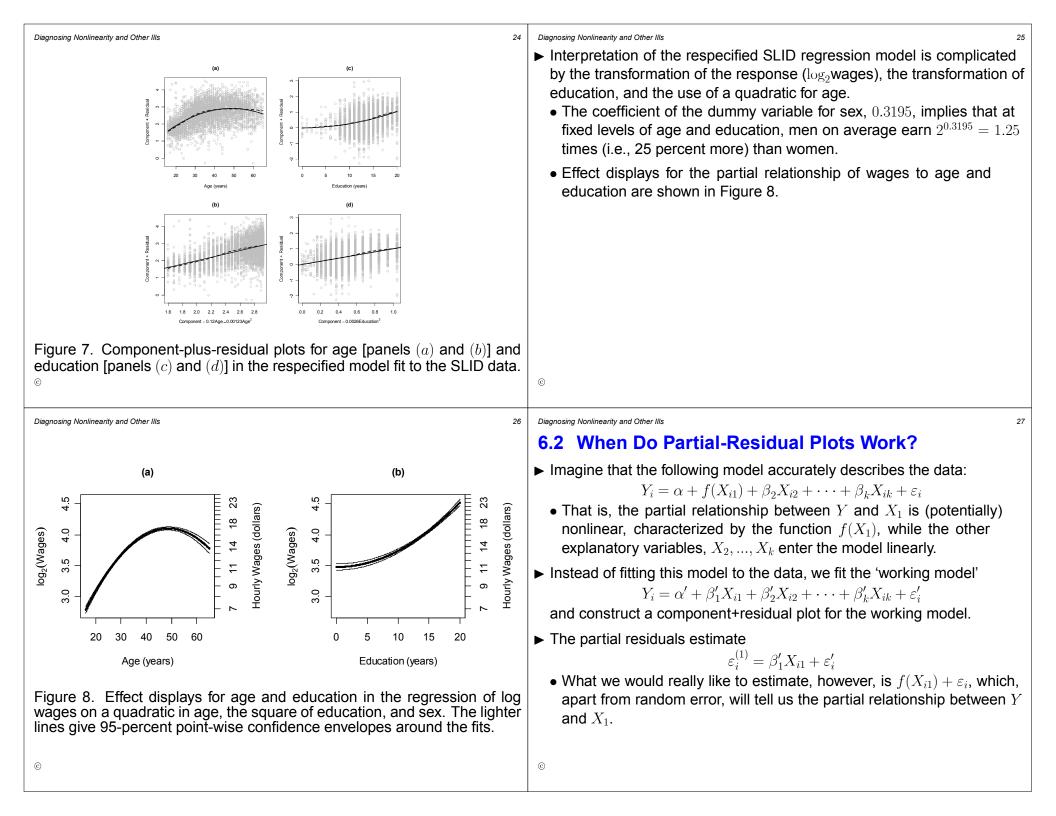
$$\widehat{Y}_i^{(Age)} = 0.1198 \times Age_i - 0.001230 \times Age_i$$

 $\widehat{Y}_i^{(Education)} = 0.002605 \times Education_i^2$

2. We can plot the partial residuals against the partial fits. See the two lower panels of Figure 7.

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21



Diagnosing Nonlinearity and Other Ills 28	Diagnosing Nonlinearity and Other Ills	29
 Cook (1993) shows that ε_i⁽¹⁾ = f(X_{i1}) + ε_i, as desired, under either of two circumstances: The function f(X₁) is linear. The other explanatory variables X₂,, X_k are each linearly related to X₁. That is, E(X_{ij}) = α_{j1} + β_{j1}X_{i1} for j = 2,, k If there are nonlinear relationships between other X's and X₁, then the component+residual plot for X₁ may appear nonlinear even if the true partial regression is linear. The second result suggests a practical procedure for improving the chances that component+residual plots will provide accurate evidence of nonlinearity: If possible, transform the explanatory variables to linearize the relationships among them. 	 Evidence suggests that weak nonlinearity is not especially problematic but strong nonlinear relationships among the explanatory variables car invalidate the component+residual plot as a useful diagnostic display. There are more sophisticated versions of component+residual plots that are more robust. 	
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Diagnosing Nonlinearity and Other Ills 30	Diagnosing Nonlinearity and Other Ills 7.1 Testing for Nonlinearity ('Lack of Fit')	31
7. Discrete Data		

- Discrete explanatory and response variables often lead to plots that are difficult to interpret, a problem that can be rectified by 'jittering' the plotted points.
 - A discrete *response* variable also violates the assumption that the errors in a linear model are normally distributed.
 - Discrete *explanatory* variables, in contrast, are perfectly consistent with the general linear model, which makes no distributional assumptions about the *X*'s, other than independence between the *X*'s and the errors.
 - Because it partitions the data into groups, a discrete *X* (or combination of *X*'s) facilitates straightforward tests of nonlinearity and non-constant error variance.

- Recall the data on vocabulary and education collected in the U.S. General Social Survey. Years of education in this dataset range between 0 and 20 (see Figure 9). We model the relationship between vocabulary score and education in two ways:
- 1. Fit a linear regression of vocabulary on education:

$$Y_i = \alpha + \beta X_i + \varepsilon_i \tag{Model 1}$$

2. Model education with a set of 20 dummy regressors (treating 0 years as the baseline category):

$$Y_i = \alpha' + \gamma_1 D_{i1} + \gamma_2 D_{i2} + \dots + \gamma_{20} D_{i,20} + \varepsilon'_i$$
(Model 2)

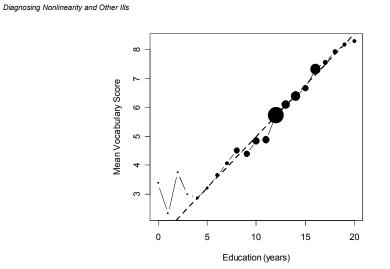


Figure 9. Mean vocabulary score by years of education. The size of the points is proportional to the number of observations. The broken line is the least-squares line.

Diagnosing Nonlinearity and Other Ills

32

- ► Contrasting the two models produces a test for nonlinearity, because the first model, specifying a linear relationship between vocabulary and education, is a special case of the second, which can capture *any* pattern of relationship between *E*(*Y*) and *X*.
 - The resulting incremental *F*-test for nonlinearity appears in the following ANOVA table:

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Source	SS	df	F	р
Education				
(Model Model 2)	26,099	20	374.44	$\ll .0001$
Linear				
(Model Model 1)	25,340	1	7,270.99	$\ll .0001$
Nonlinear				
("lack of fit")	759	19	11.46	$\ll .0001$
Error				
("pure error")	75,337	21,617		
Total	101,436	21,637		

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- Note that while it is highly statistically significant, the nonlinear component accounts for very little of the variation in vocabulary scores.
- ► The incremental *F*-test for nonlinearity can easily be extended to a discrete explanatory variable say X₁ in a multiple-regression model.
 - Here, we need to contrast the general model

 $Y_i = \alpha + \gamma_1 D_{i1} + \dots + \gamma_{m-1} D_{i,m-1} + \beta_2 X_{i2} + \dots + \beta_k X_{ik} + \varepsilon_i$ with the model specifying a linear effect of X_1 ,

 $Y_i = \alpha + \beta_1 X_{i1} + \beta_2 X_{i2} + \dots + \beta_k X_{ik} + \varepsilon_i$

where $D_1, ..., D_{m-1}$ are dummy regressors constructed to represent the *m* categories of X_1 .

Diagnosing Nonlinearity and Other Ills

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34

7.2 Testing for Non-Constant Error Variance

- ► A discrete X (or combination of X's) partitions the data into m groups (as in analysis of variance).
 - Let Y_{ij} denote the *i*th of n_j response-variable scores in group *j*.
 - If the error variance is constant across groups, then the within-group sample variances

$$S_{j}^{2} = \frac{\sum_{i=1}^{n_{j}} (Y_{ij} - \overline{Y}_{j})^{2}}{n_{j} - 1}$$

should be similar.

– Tests that examine the S_j^2 directly do not maintain their validity well when the distribution of the errors is non-normal.

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powerful: • Calculate the values $Z_{ij} \equiv |Y_{ij} - \widetilde{Y}_j|$ where \tilde{Y}_{i} is the median response-variable value in group j. • Then perform a one-way analysis-of-variance of the Z_{ii} over the mnumbers of individuals with very low levels of education). groups. • If the error variance is not constant across the groups, then the group means \overline{Z}_i will tend to differ, producing a large value of the *F*-test statistic. c c Diagnosing Nonlinearity and Other Ills Diagnosing Nonlinearity and Other Ills 38 Maximum-Likelihood Methods 8. 3.0 \blacktriangleright A statistically sophisticated approach to selecting a transformation of Y 2.8 or an X is to imbed the linear model in a more general nonlinear model that contains a parameter for the transformation.

36

- If several variables are potentially to be transformed then there may be several such parameters.
- Suppose that the transformation is indexed by a single parameter λ , and that we can write down the likelihood for the model as a function of the transformation parameter and the usual regression parameters: $L(\lambda, \alpha, \beta_1, ..., \beta_k, \sigma_{\varepsilon}^2).$
 - Maximizing the likelihood yields the maximum-likelihood estimate of λ along with the MLEs of the other parameters.
 - Now suppose that $\lambda = \lambda_0$ represents *no* transformation (e.g., $\lambda_0 = 1$ for the power transformation Y^{λ}).

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▶ The following simple *F*-test (called Levene's test) is both robust and

Diagnosing Nonlinearity and Other Ills

• For the vocabulary data, where education partitions the 21,638 observations into m = 21 groups, $F_0 = 4.26$, with 20 and 21,617 degrees of freedom, for which $p \ll .0001$. There is, therefore, strong evidence of non-constant spread in vocabulary across the categories of education, though, as revealed in Figure 10, the within-group standard deviations are not very different (discounting the small

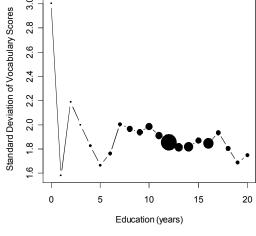


Figure 10. Standard deviation of vocabulary scores by education. The

39

- A likelihood-ratio test, Wald test, or score test of $H_0: \lambda = \lambda_0$ assesses the evidence that a transformation is required.
- A disadvantage of the likelihood-ratio and Wald tests is that they require finding the MLE, which usually requires iteration.
 - In contrast, the slope of the log-likelihood at λ_0 on which the score test depends generally can be assessed or approximated without iteration.
 - Often, the score test can be formulated as the *t*-statistic for a new regressor, called a *constructed variable*, to be added to the linear model.
- Moreover, a partial-regression plot for the constructed variable then can reveal whether one or a small group of observations is unduly influential in determining the transformation.

8.1 Box-Cox Transformation of *Y*

- ► Box and Cox suggest power transformation of *Y* with the object of normalizing the error distribution.
- ► The general Box-Cox model is

 $Y_i^{(\lambda)} = \alpha + \beta_1 X_{i1} + \dots + \beta_k X_{ik} + \varepsilon_i$ where the errors ε_i are independently $N(0, \sigma_c^2)$, and

• Note that all of the Y_i must be positive.

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- ► A simple procedure for finding the MLE is to evaluate the maximized $\log_e L(\alpha, \beta_1, ..., \beta_k, \sigma_{\varepsilon}^2 | \lambda)$ for a range of values of λ , say between -2 and +2.
 - If this range turns out not to contain the maximum of the log-likelihood, then the range can be expanded.
 - To test H_0 : $\lambda = 1$, calculate the likelihood-ratio statistic

$$C_{0}^{2} = -2[\log_{e} L(\lambda = 1) - \log_{e} L(\lambda = \widehat{\lambda})]$$

which is asymptotically distributed as χ^2 with one degree of freedom under H_0 .

 \bullet Equivalently, a 95-percent confidence interval for λ includes those values for which

 $\log_e L(\lambda) > \log_e L(\lambda = \widehat{\lambda}) - 1.92$

- The figure 1.92 comes from $1/2 \times \chi^2_{1.05} = 1/2 \times 1.96^2$.
- ► Figure 11 shows a plot of the maximized log-likelihood against λ for the original SLID regression.

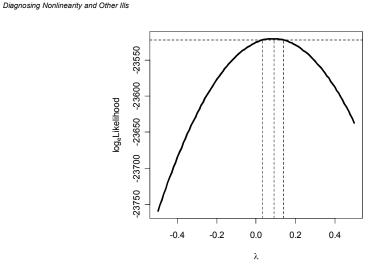


Figure 11. Box-Cox transformations for the SLID regression of wages on sex, age, and education. The maximized log likelihood is plotted against the transformation parameter λ .

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44 • The maximum-likelihood estimate of λ is $\hat{\lambda} = 0.09$, and a 95% confidence interval, marked out by the intersection of the line near the top of the graph with the profile log likelihood, runs from 0.04 to 0.13. ► Atkinson has proposed an approximate score test for the Box-Cox model, based on the constructed variable $G_i = Y_i \left[\log_e \left(\frac{Y_i}{\widetilde{V}} \right) - 1 \right]$ where \widetilde{Y} is the *geometric mean* of *Y*: $\widetilde{Y} \equiv (Y_1 \times Y_2 \times \cdots \times Y_n)^{\frac{1}{n}}$ • The augmented regression, including the constructed variable, is then $Y_i = \alpha + \beta_1 X_{i1} + \dots + \beta_k X_{ik} + \phi G_i + \varepsilon_i$ • The *t*-test of H_0 : $\phi = 0$, that is, $t_0 = \hat{\phi}/\mathsf{SE}(\hat{\phi})$, assesses the need for a transformation. c c Diagnosing Nonlinearity and Other Ills 46 30 20 Vages | Others 9 0 20 20 25 10 15 Constructed Variable | Others

Figure 12. Constructed-variable plot for the Box-Cox transformation of wages in the SLID regression. The least-squares line is shown on the plot.

Diagnosing Nonlinearity and Other Ills

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8.2 Box-Tidwell Transformation of the X's

► Now, consider the model

$$Y_i = \alpha + \beta_1 X_{i1}^{\gamma_1} + \dots + \beta_k X_{ik}^{\gamma_k} + \varepsilon_i$$

where the errors are independently distributed as $\varepsilon_i \sim N(0, \sigma_{\varepsilon}^2)$, and all of the X_{ii} are positive.

- ▶ The parameters of this model $\alpha, \beta_1, ..., \beta_k, \gamma_1, ..., \gamma_k$, and σ_{ε}^2 could be estimated by general nonlinear least squares, but Box and Tidwell suggest instead a computationally more efficient procedure that also vields a constructed-variable diagnostic:
- 1. Regress Y on X_1, \ldots, X_k , obtaining A, B_1, \ldots, B_k .
- 2. Regress Y on $X_1, ..., X_k$ and the constructed variables $X_1 \log_e X_1, ..., X_k \log_e X_k$, obtaining $A', B'_1, ..., B'_k$ and $D_1, ..., D_k$.

- An estimate of λ (though not the MLE) is given by $\tilde{\lambda} = 1 \hat{\phi}$.
- The added-variable plot for the constructed variable G shows influence and leverage on ϕ , and hence on the choice of λ .

45

- Atkinson's constructed-variable plot for the interlocking-directorate regression is shown in Figure 12.
 - The coefficient of the constructed variable in the regression is $\hat{\phi} = 1.454$, with SE($\hat{\phi}$) = 0.026, providing overwhelmingly strong evidence of the need to transform Y.

- The suggested transformation, $\tilde{\lambda} = 1 - 1.454 = -0.454$, is far from the MI F

is given by

 $\widehat{\gamma}_i$.

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- ► Consider the SLID regression of log wages on sex, education, and age.
 - The dummy regressor for sex is not a candidate for transformation, of course, but I will consider power transformations of age and education.
 - Recall that we were initially undecided about whether to model the age effect as a quadratic or as a transformation down the ladder of powers and roots.
 - To make power transformations of age more effective, I use a negative start of 15 (recall that age ranges from 16 to 65).
 - The coefficients of $(Age -15) \times \log_e(Age -15)$ and Education× $\log_e \text{Education}$ in the step-2 augmented model are, respectively, $D_{Age} = -0.04699$ with $\text{SE}(D_{Age}) = 0.00231$, and $D_{\text{Education}} = 0.05612$ with $\text{SE}(D_{\text{Education}}) = 0.01254$.
 - Both score tests are statistically significant, but there is much stronger evidence of the need to transform age.

Diagnosing Nonlinearity and Other Ills

 $\widehat{\gamma}$

• The first-step estimates of the transformation parameters are

$$\widetilde{\gamma}_{\text{Age}} = 1 + \frac{D_{\text{Age}}}{B_{\text{Age}}} = 1 + \frac{-0.04699}{0.02619} = -0.79$$

$$\widetilde{\gamma}_{\text{Education}} = 1 + \frac{D_{\text{Education}}}{B_{\text{Education}}} = 1 + \frac{0.05612}{0.08061} = 1.69$$

3. The constructed variable $X_j \log_e X_j$ can be used to assess the need for a transformation of X_i by testing the null hypothesis H_0 : $\delta_i = 0$, where

 δ_i is the population coefficient of $X_i \log_e X_i$ in step 2. Added-variable

4. A preliminary estimate of the transformation parameter γ_i (not the MLE)

 $\widetilde{\gamma}_j = 1 + \frac{D_j}{B_i}$

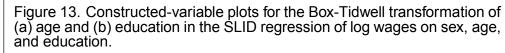
estimates of the transformation parameters stabilize, yielding the MLEs

▶ This procedure can be iterated through steps 1, 2, and 4 until the

influence on the decision to transform the X's.

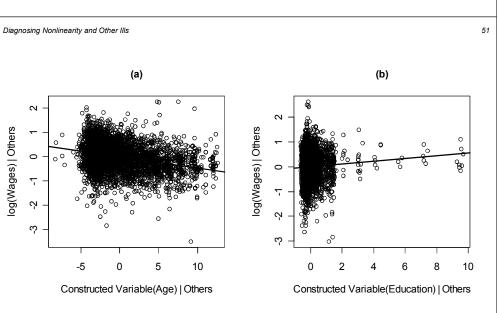
plots for the constructed variables are useful for assessing leverage and

- The fully iterated MLEs of the transformation parameters are $\hat{\gamma}_{Age} = 0.051$ and $\hat{\gamma}_{Education} = 1.89$ very close to the log transformation of started-age and the square of education.
- Constructed-variable plots for the transformation of age and education are shown in Figure 13.



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Diagnosing Nonlinearity and Other Ills 52	Diagnosing Nonlinearity and Other Ills 53
8.3 Non-Constant Error Variance Revisited	• Breusch and Pagan show that the score statistic $\sum (\widehat{U} - \overline{U})^2$
 Breusch and Pagan develop a score test for heteroscedasticity based on the specification: σ_i² ≡ V(ε_i) = g(γ₀ + γ₁Z_{i1} + ··· + γ_pZ_{ip}) where Z₁,, Z_p are known variables, and where the function g(·) is quite general. The same test was independently derived by Cook and Weisberg. The score statistic for the hypothesis that the σ_i² are all the same, which is equivalent to H₀: γ₁ = ··· = γ_p = 0, can be formulated as an auxiliary-regression problem. Let U_i ≡ E_i²/σ_ε², where σ_ε² = ∑ E_i²/n is the MLE of the error variance. Regress U on the Z's: U_i = η₀ + η₁Z_{i1} + ··· + η_pZ_{ip} + ω_i 	 S₀² = ∑(Û_i - Ū)²/2 is asymptotically distributed as χ² with <i>p</i> degrees of freedom under the null hypothesis of constant error variance. Here, the Û_i are fitted values from the regression of <i>U</i> on the <i>Z</i>'s, and thus S₀² is half the regression sum of squares from the auxiliary regression. To apply this result, it is necessary to select <i>Z</i>'s, the choice of which depends upon the suspected pattern of non-constant error variance. Employing X₁,, X_k in the auxiliary regression, for example, permits detection of a tendency of the error variance to increase (or decrease) with the values of one or more of the explanatory variables in the main regression.
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 Diagnosing Nonlinearity and Other Ills Cook and Weisberg suggest regressing U on the fitted values from the main regression (i.e., U_i = η₀ + η₁Ŷ_i + ω_i), producing a one-degree-of-freedom score test to detect the common tendency of the error variance to increase with the level of the response variable. Anscombe suggests correcting detected heteroscedasticity by transforming Y to Y^(X) with X = 1 - 1/2 η₁Y. Applied to the initial SLID regression of wages on sex, age, and education, an auxiliary regression of U on Ŷ yields Û = -0.3449 + 0.08652Ŷ, and S₀² = 567.66/2 = 283.83 on 1 degree of freedom, for which p ≈ 0. The suggested variance-stabilizing transformation using Anscombe's rule is	Diagnosing Nonlinearity and Other Ills 55 • An auxiliary regression of U on the explanatory variables in the main regression yields $S_0^2 = 579.08/2 = 289.54$ on $k = 3$ degrees of freedom. – The score statistic for the more general test is not much larger than that for the regression of U on \hat{Y} , implying that the pattern of non-constant error variance is indeed for the spread of the errors to increase with the level of Y .
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Diagnosing Nonlinearity and Other IIIs 56	Diagnosing Nonlinearity and Other Ills 57
 9. Summary Heavy-tailed errors threaten the efficiency of least-squares estimation; skewed and multimodal errors compromise the interpretation of the least-squares fit. Non-normality can often be detected by examining the distribution of the least-squares residuals, and frequently can be corrected by transforming the data. It is common for the variance of the errors to increase with the level of the response variable. This pattern of non-constant error variance can often be detected in a plot of residuals against fitted values. 	 Strategies for dealing with non-constant error variance include transformation of the response variable to stabilize the variance; the substitution of weighted-least-squares estimation for ordinary least squares; and the correction of coefficient standard errors for heteroscedasticity. A rough rule of thumb is that non-constant error variance seriously degrades the least-squares estimator only when the ratio of the largest to smallest variance is about 10 or more. Simple forms of nonlinearity can often be detected in component+residual plots. Once detected, nonlinearity can frequently be accommodated by variable transformations or by altering the form of the model (to include a quadratic term in an explanatory variable, for example). Component+residual plots adequately reflect nonlinearity when the explanatory variables are themselves not strongly nonlinearly related.
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Diagnosing Nonlinearity and Other IIIs 58	Diagnosing Nonlinearity and Other Ills 59
 Discrete explanatory variables divide the data into groups. A simple incremental <i>F</i>-test for nonlinearity compares the sum of squares accounted for by the linear regression of <i>Y</i> on <i>X</i> with the sum of squares accounted for by differences in the group means. Likewise, tests of non-constant variance can be based upon comparisons of spread in the different groups. 	Simple score tests are available to determine the need for a transforma- tion and to test for non-constant error variance.
 A statistically sophisticated general approach to selecting a transformation of <i>Y</i> or an <i>X</i> is to imbed the linear-regression model in a more general model that contains a parameter for the transformation. The Box-Cox procedure selects a power transformation of <i>Y</i> to normalize the errors. 	
• The Box-Tidwell procedure selects power transformations of the <i>X</i> 's to linearize the regression of <i>Y</i> on the <i>X</i> 's.	
 In both cases, 'constructed-variable' plots help us to decide whether individual observations are unduly influential in determining the transformation parameters. 	
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